

# Testing Ethical Decision-Making in Autonomous Systems

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Jan65 Fest!

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Based on joint work with: Michael Akintunde, Martim Brandao, Gunel Jahangirova, Hector Menendez, and Jie Zhang

For Jan Peleska, Who has a passion for going through all scenarios, While standing on firm grounds....

Happy Birthday Jan and Many happy scenarios!



Prelude: Trust in Autonomous systems

# **MISSION STATEMENT**

### We apply **rigorous analysis** techniques to ensure **safety** and to establish **trust** in **autonomous systems**.

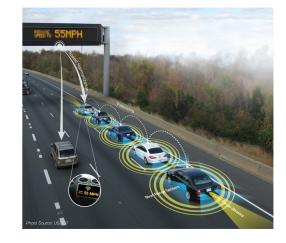


### **Trust: Definition and Facets**

- User's belief that a system's performance is helpful and safe, particularly in uncertain and critical situations
- Major contributors:
  - Technical transparency (design intentions)
  - Explainability
  - Safety and Security
  - User experience

### **Connected Platoons**

- Main idea: rigorous safety analysis of design space for autonomous functions
- Approach:
  - **Conformance testing**: comparing the behaviour of an "ideal platoon" with a parameterised implementation
  - Genetic algorithms and search-based techniques
    - Maximising risk
       pushing the system towards failure
  - Analysing the outcomes and finding optimal parameters
- Application:
  - Increase trust by improving the safety and performance of basic awareness protocols in connected autonomous functions



[Araujo, Hoenselaar, MRM and Vinel. PIRMC 2020]

### **Particle Emission Tests**

- Main Idea: design effective particle emission tests using a combination of machine learning and conformance testing
- Approach:
  - Use real data (from NOx sensors) to learn a model of vehicle's behavior
  - Run search-based techniques to maximise emission under given test constraints



- Applications:
  - Detecting cheaters: **doping tests**, e.g., for diesel cars
  - Designing environment-friendly profiles for autonomous vehicles
- Trust through transparency

[Dimitrova, Gazda, MRM, Biewer, Hermanns, FORTE 2020] [idem, Fries, Heinze, LMCS 2022]

### **Adaptive Model Learning**

- Main idea: learn succinct models that summarise spatial and temporal evolution of systems
- Approach:
  - Carefully observing redundant and deprecated queries in automata learning
  - Summarising models learned from various products; making the process efficient for small sample sizes
- Application:
  - Increase trust by providing models explaining system evolution



## **KASPAR EXPLAINS**

- Main Idea: how causal explanation can influence stakeholders' trust
- Approach:
  - Analysing interaction videos
  - Formalising interactions in behavioural models
  - Generating causal explanations for various stakeholder
- Applications:
  - Kaspar: an educational robot for autistic children
- Trust through explanation



KASPAR

University of Hertfordshire





http://bit.ly/KasparExplains [Araujo et al. ICSR 2022] [Sarda Gou et al. RO-MAN 2022]



## https://verifiability.org



# Zooming In: Testing Ethics

Ongoing joint work with: Michael Akintunde, Martim Brandao, Gunel Jahangirova, Hector Menendez, and Jie Zhang

# **Testing Ethics: Why?**

- Machines making ethically-charged decisions:
  - Environmental impact of vehicle control
  - Fairness implications of credit scoring and financial decisions
- Need for a discipline of testing cases and oracles improve
  - Transparency and balance conflicting interests of stakeholders
  - Understanding ethics

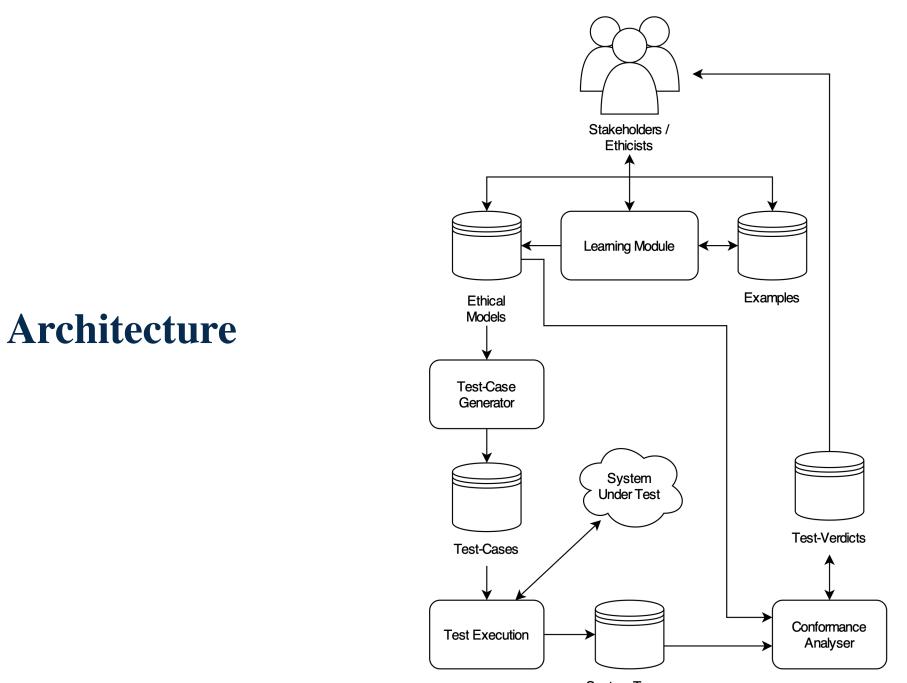
"AI makes Philosophy honest."

– D. Dennett Computers as Prostheses for Imagination

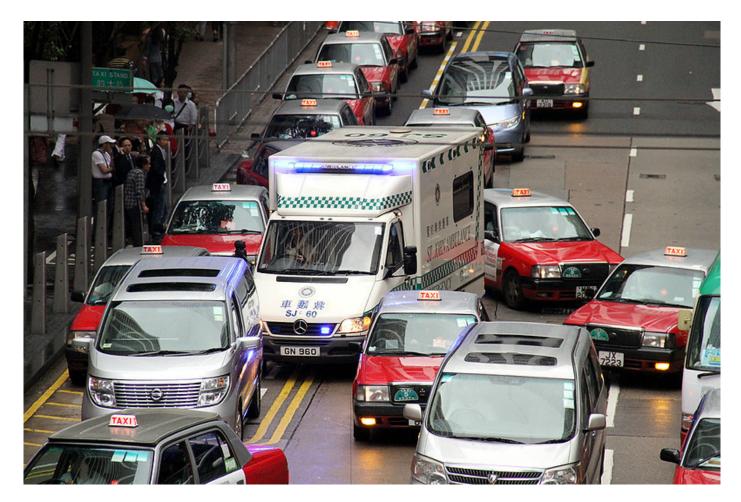
### **Testing Ethics: Challenges**

- Generating effective scenarios
- Different meta-ethical frameworks
- Ethical oracles
- Diversity and stakeholder engagement





#### **Testing Ethics: Running Example**



Copyright: C. Junker, Flickr, CC2.0

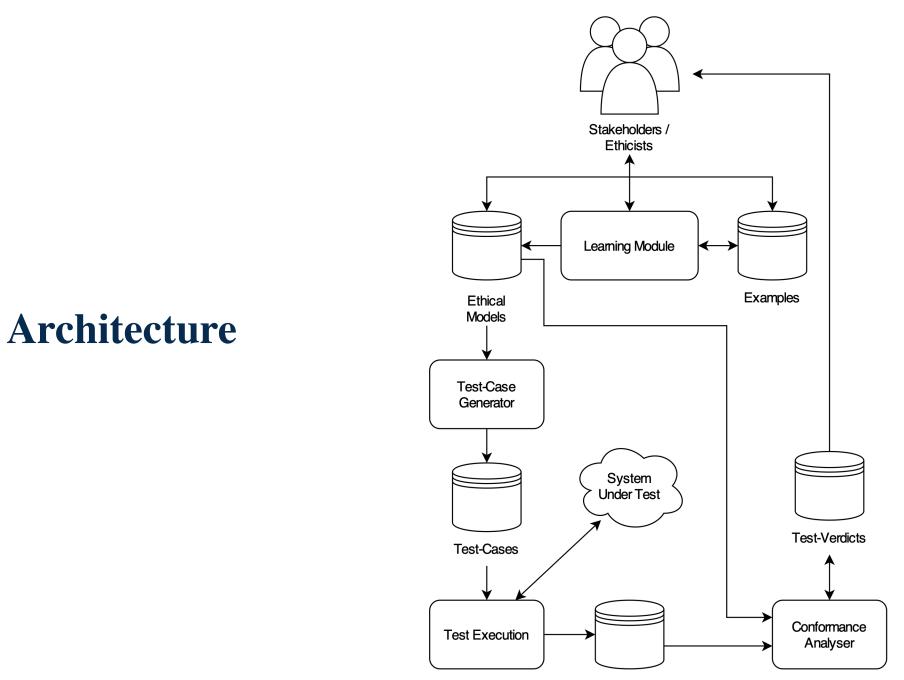
### **Scenario Generation Ethics: Challenges**

- Objectives:
  - Efficient / effective fault detection
  - Useful vehicles for user engagement
- Diversity and coverage
- Scenarios that:

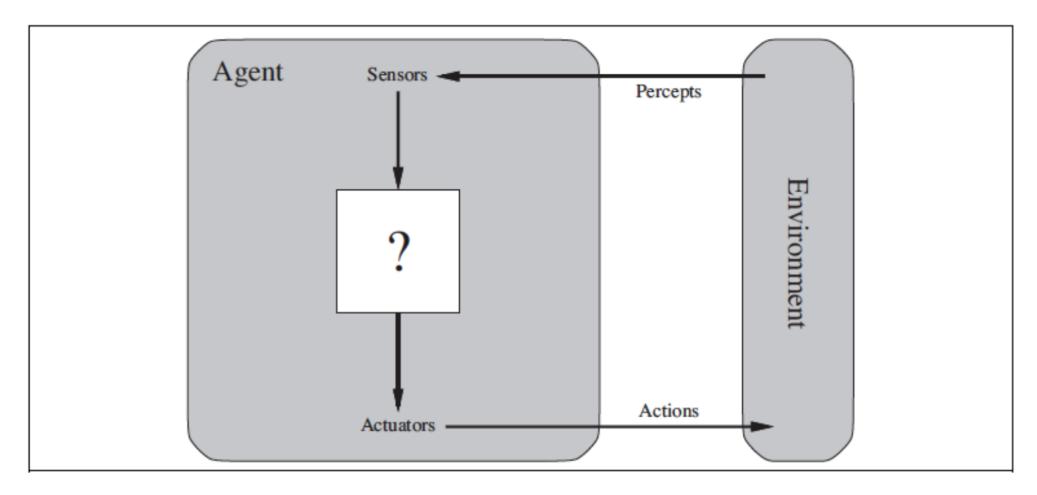
conformance to various parts of the highway code,choices between the code and giving way emergency vehicles

Covering various combinations of ethical objectives / regulations



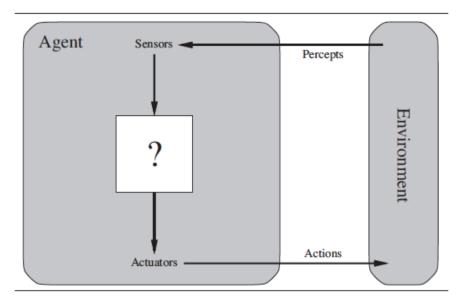


#### **Test Oracles: Metaphor**

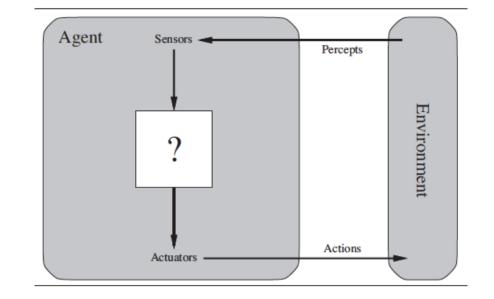


From: Russel and Norvig, Artificial Intelligence: A Modern Approach. p. 35, Prentice Hall.

- Meta-ethics:
  - Deontologicism: acts are inherently good or evil
  - Consequentialism (Utilitarianism):acts are good or evil because of (depending on) their consequences
  - Virtue ethics: an action is good or evil if it it fits for (improves) a virtuous person
- Many variants, taking various environmental conditions into account:
  - Prima facie duty

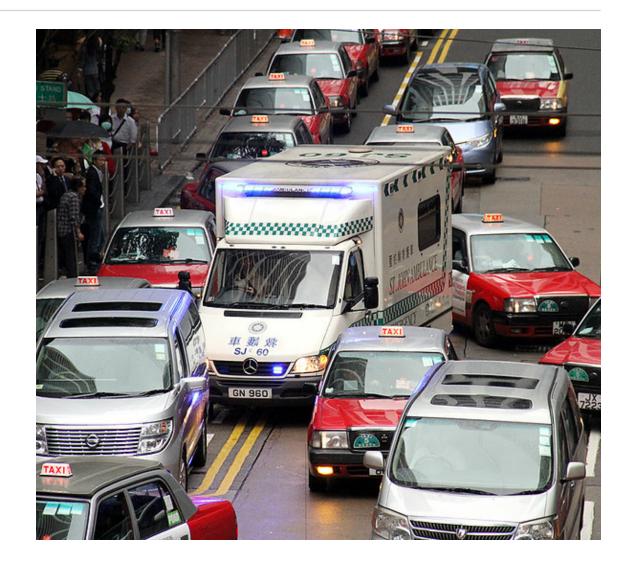


- Oracle for a deontological theory
  - **Objective** Obj: Action  $\rightarrow$  Value
  - Test input  $\alpha$ : *Percept*\*
  - **Test output** a after  $\alpha$ : Action. (last observed action)
  - Verdict  $|Obj(a \ after \ \alpha) Obj \ (ideal \ after \ \alpha)| \le \varepsilon$
- Problems:
  - Values of actions:
    - Partial orders among actions
  - Optimal  $\alpha$  : search-based testing
  - Correct *ideal after*  $\alpha$  : Surrogate models
  - Threshold  $\varepsilon$  : domain knowledge

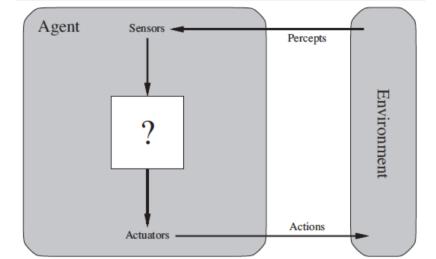


[Ganascia, Ethical System Formalization using Non-Monotonic Logics, 2007]

- an agent shall respect human lives, obj(kill) = -1
- an agent shall give way to ambulances, obj(give\_way) = +1 and
- an agent shall not damage other cars obj(damage) = -1



- Oracle for act-utilitarianism:
  - **Objective** Obj:  $Action \times Env \rightarrow Value$
  - **Test input**  $(\alpha, env)$ :  $Percept^* \times Env$
  - **Test output** *a after*  $\alpha$ : *Action*. (last observed action)
  - Verdict  $|Obj(a \ after \ \alpha, env) Obj (ideal \ after \ \alpha, env)| \leq \varepsilon$
- Problems:
  - Similar problems as to deontological ethics
  - Richer value models
  - Conflicts with deontological theory

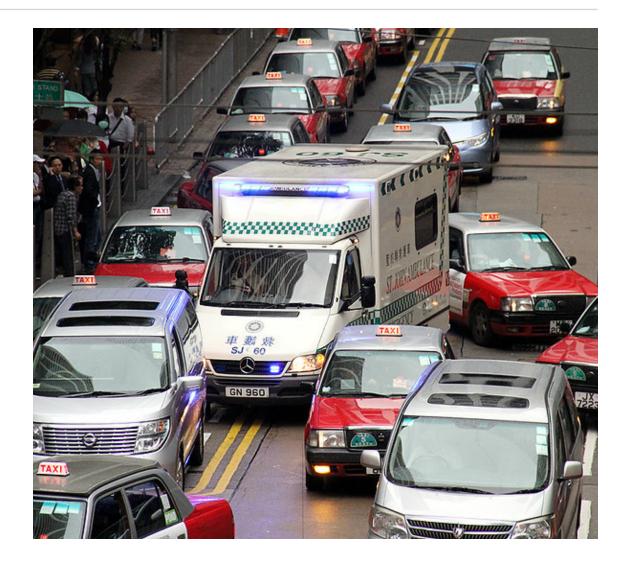


• an agent shall respect human lives at all times,

 $\forall env. obj(kill, env) = -100$ 

 an agent shall give way to ambulances if it does not involve a damage to other cars,

 $\forall env. giveway \bowtie damage$  $\Rightarrow obj(giveway, env) = +10$ 



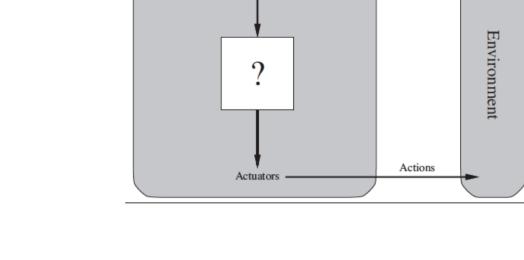
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Elisabeth Halvorsen, Bachelor Thesis, KCL.

- Oracle for virtue-ethics:
- Model of a moral exemplar S (robotic saint!)
   Conformance btw. agent A and exemplar:
- distance of their
  - states
  - output sequences

under the same input sequence.

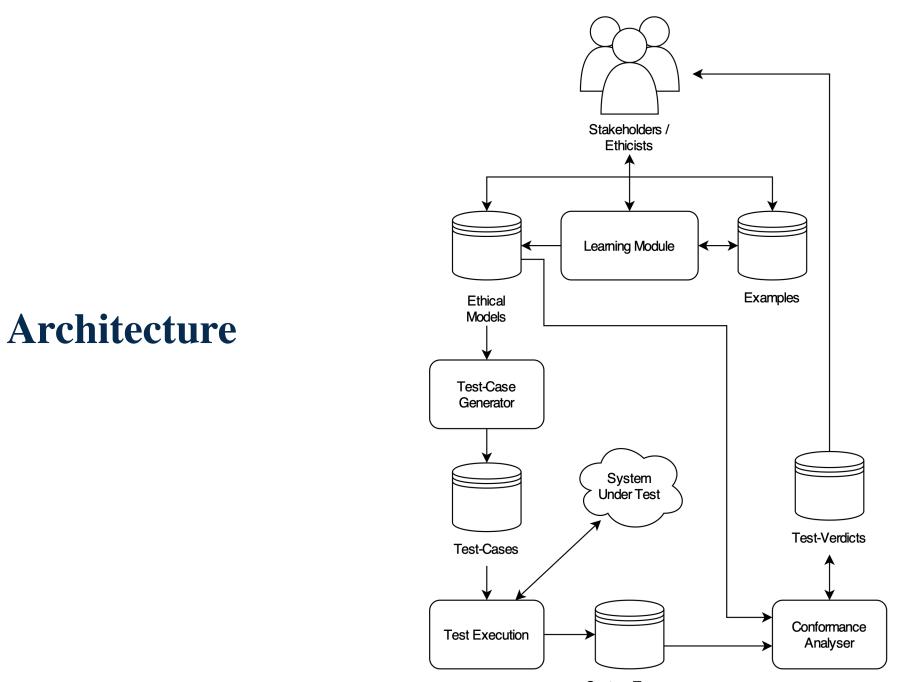
```
• \forall \alpha: (Percept^* \times Action)^* . \alpha \in beh(agent)
\forall \beta: (Percept^* \times Action)^* . \beta \in beh(saint).
dist(\alpha, \beta) \le \epsilon
```



Sensors

Percepts

Agent





# Thank you

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