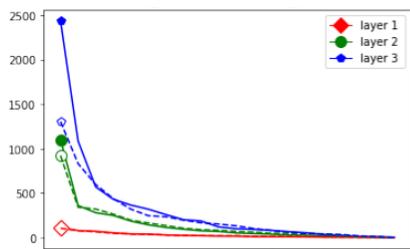


Singular Values for ReLU Layers

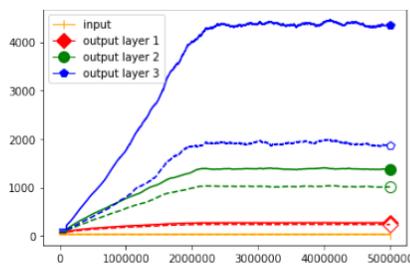
- We generalize singular values to ReLU layers and used them and the Gaussian mean width to analyze the behavior of data inside neural networks.
- Definition of (data independent) ReLU singular values:

$$s_k = \min_{\text{rank } L \leq k} \max_{x \in \mathcal{B}} \|\text{ReLU}(Ax) - \text{ReLU}(Lx)\|_2. \quad (1)$$

Data dependent ReLU singular values of a network. Misclassified (dashed) vs. correctly classified (solid) data.



The Gaussian mean width of the data after different layers over the course of the training. Again misclassified vs. correctly classified data.



Published: IEEE Transactions on Neural Networks and Learning Systems

Regularization by architecture

- We analyze the idea of the Deep image prior (DIP) in terms of a variational formulation and the implicit function theorem to find closed form solutions for special cases.
- The DIP idea: Solve an inverse problem via

$$\min_{\theta} \|A\varphi_B(z) - y^\delta\|^2, \quad (2)$$

where $\varphi_B(z)$ is an untrained neural net with parameters B and a fixed random input z .

We analyze infinitely deep recurrent networks consisting of layers of the form

$$x^{k+1} = \text{prox}_{\lambda\alpha R} \left(x^k - \lambda B^*(Bx^k - y^\delta) \right). \quad (3)$$

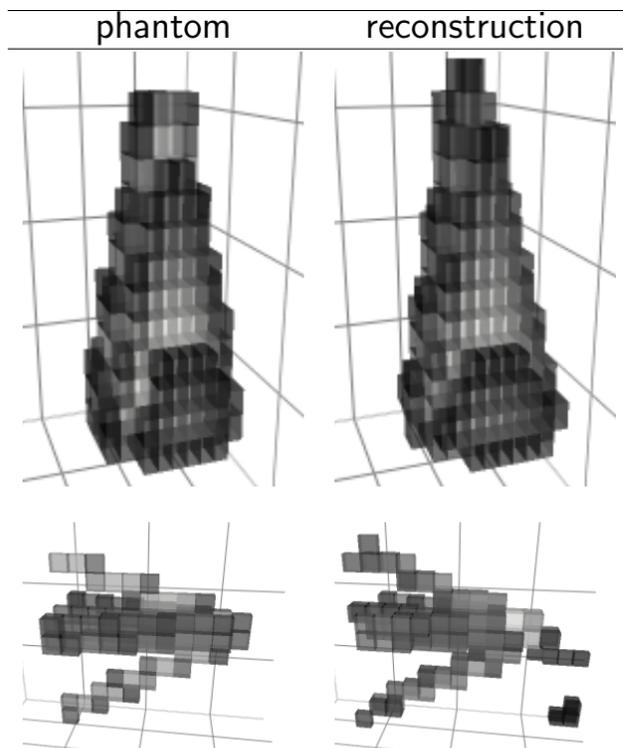
For these nets the solution can be rewritten via the implicit function theorem and efficiently analyzed. E.g., for the case $R(x) = \frac{1}{2}\|x\|^2$, one finds that the problem simply reduces to

$$\min_B \frac{1}{2} \|A(B^*B + \alpha I)^{-1} B^* y^\delta - y^\delta\|^2. \quad (4)$$

Published: Springer, Journal of Mathematical Imaging and Vision

Deep image prior for 3D magnetic particle imaging

- We created a DIP (see explanation in top right of the poster) with a three-dimensional architecture such that we could apply it to the preclinical imaging modality "magnetic particle imaging" (MPI)
- We created a large scale comparison between it and classical reconstruction methods used for MPI based on the Open MPI dataset.
- We found that overall our DIP approach outperformed all classical methods in terms of PSNR and SSIM.



Ground Truth Free Denoising by Optimal Transport

- The idea is to denoise data based on noise samples (from a distribution p_η) and noisy samples (from a distribution p_{y^δ}) only.
- We only assume that the noise is independent of the data and additive.
- We start out by assuming that a perfect denoiser G^* has the properties:

$$(G^*_{\#} p_{y^\delta}) * p_\eta = p_{y^\delta}, \quad (5)$$

and

$$(\text{id} - G^*)_{\#} p_{y^\delta} = p_\eta. \quad (6)$$

- We train a network G to approximate a solution to these equations in terms of the Wasserstein metric. We do so by formulating the problems as a novel Wasserstein Generative Adversarial Network setting.
- We find for different scenarios (including images) that we are on par or better than state-of-the-art unsupervised denoisers like BM3D.

